

EXISTENCE AND UNIQUENESS THEOREMS FOR SOME COMMON FIXED POINTS IN HAUSDORFF UNIFORM SPACES

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ABSTRACT. In this paper, we prove some existence and uniqueness theorems for some common fixed point theorems in Hausdorff uniform spaces for selfmappings using the concepts of A -distance and E -distance. A class of ψ -contractive condition more general than those of Aamri and El Moutawakil [1], Olatinwo [13] and Bosede [6] was employed to establish our results. Our generalizations can be viewed as an improvement to some of the known results in literature.

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1. INTRODUCTION

Several authors such as Berinde [2], Jachymski [10], Kada et al [11], Rhoades [14], Rus [16], Wang et al [18] and Zeidler [19] studied the theory of fixed point or common fixed point for contractive self-mappings in complete metric spaces or Banach spaces in general. Within the last two decades, Kang [12], Rodríguez-Montes and Charris [15] established some results on fixed and coincidence points of maps by means of appropriate W -contractive or W -expansive assumptions in uniform space.

In the sequel we shall define a uniform space as follows: Let X be a nonempty set and let Φ be a nonempty family of subsets of $X \times X$. The pair (X, Φ) is called a uniform space if it satisfies the following properties:

- (i) if G is in Φ , then G contains the diagonal $\{(x, x) | x \in X\}$;
- (ii) if G is in Φ and H is a subset of $X \times X$ which contains G , then H is in Φ ;
- (iii) if G and H are in Φ , then $G \cap H$ is in Φ ;
- (iv) if G is in Φ , then there exists H in Φ , such that, whenever (x, y) and (y, z)

are in H , then (x, z) is in H ;

(v) if G is in Φ , then $\{(y, x) | (x, y) \in G\}$ is also in Φ .

Φ is called the uniform structure of X and its elements are called entourages or neighbourhoods or surroundings.

If property (v) is omitted, then (X, Φ) is called a quasiuniform space. [For examples, see Bourbaki [9] and Zeidler [19]].

In 2004, Aamri and El Moutawakil [1] proved some common fixed point theorems for some new contractive or expansive maps in uniform spaces by introducing the notions of an A -distance and an E -distance.

Aamri and El Moutawakil [1] introduced and employed the following contractive definition: Let $f, g : X \rightarrow X$ be selfmappings of X . Then, we have

$$p(f(x), f(y)) \leq \psi(p(g(x), g(y))), \quad \forall x, y \in X \quad (1)$$

where $\psi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is a nondecreasing function satisfying

(i) for each $t \in (0, +\infty)$, $0 < \psi(t)$,

(ii) $\lim_{n \rightarrow \infty} \psi^n(t) = 0$, $\forall t \in (0, +\infty)$.

ψ satisfies also the condition $\psi(t) < t$, for each $t > 0$.

In 2007, Olatinwo [13] established some common fixed point theorems by employing the following contractive definition: Let $f, g : X \rightarrow X$ be selfmappings of X . There exist $L \geq 0$ and a comparison function $\psi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that $\forall x, y \in X$, we have

$$p(f(x), f(y)) \leq Lp(x, g(x)) + \psi(p(g(x), g(y))), \quad \forall x, y \in X \quad (2)$$

Recently, the author [6] proved some common fixed point theorems by employing the following contractive definition: Let $f, g : X \rightarrow X$ be selfmappings of X . There exist comparison functions $\psi_1 : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ and $\psi_2 : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ with $\psi_1(0) = 0$ such that $\forall x, y \in X$, we have

$$p(f(x), f(y)) \leq \psi_1(p(x, g(x))) + \psi_2(p(g(x), g(y))), \quad \forall x, y \in X \quad (3)$$

In this paper, we shall establish some common fixed point theorems by using a contractive condition more general than (1), (2) and (3).

We shall also employ the concepts of an A -distance, an E -distance as well as the notion of comparison function in this paper.

2. PRELIMINARY

The following definitions contained in Aamri and El Moutawakil [1] shall be required in the sequel: Let (X, Φ) be a uniform space

and $(X, \tau(\Phi))$ a topological space whenever topological concepts are mentioned in the context of a uniform space (X, Φ) .

Definition 1. If $H \in \Phi$ and $(x, y) \in H, (y, x) \in H$, x and y are said to be H -close. A sequence $\{x_n\}_{n=0}^\infty \subset X$ is said to be a *Cauchy sequence* for Φ if for any $H \in \Phi$, there exists $N \geq 1$ such that x_n and x_m are H -close for $n, m \geq N$.

Definition 2. A function $p : X \times X \rightarrow \mathbb{R}^+$ is said to be an *A-distance* if for any $H \in \Phi$, there exists $\delta > 0$ such that if $p(z, x) \leq \delta$ and $p(z, y) \leq \delta$ for some $z \in X$, then $(x, y) \in H$.

Definition 3. A function $p : X \times X \rightarrow \mathbb{R}^+$ is said to be an *E-distance* if

- (p₁) p is an *A-distance*,
- (p₂) $p(x, y) \leq p(x, z) + p(z, y), \forall x, y \in X$.

Definition 4. A uniform space (X, Φ) is said to be *Hausdorff* if and only if the intersection of all $H \in \Phi$ reduces to the diagonal $\{(x, x) | x \in X\}$, i.e. if $(x, y) \in H$ for all $H \in \Phi$ implies $x = y$. This guarantees the uniqueness of limits of sequences. $H \in \Phi$ is said to be *symmetrical* if $H = H^{-1} = \{(y, x) | (x, y) \in H\}$.

Definition 5. Let (X, Φ) be a uniform space and p be an *A-distance* on X .

- (i) Sequence $\{x_n\}_{n=0}^\infty$ is *p-Cauchy* if given $\epsilon > 0$, there exists N such that if $m, n > N$, then $p(x_m, x_n) < \epsilon$.
- (ii) X is said to be *S-complete* if for every *p-Cauchy* sequence $\{x_n\}_{n=0}^\infty$, there exists $x \in X$ with $\lim_{n \rightarrow \infty} p(x_n, x) = 0$.
- (iii) X is said to be *p-Cauchy complete* if for every *p-Cauchy* sequence $\{x_n\}_{n=0}^\infty$, there exists $x \in X$ with $\lim_{n \rightarrow \infty} x_n = x$ with respect to $\tau(\Phi)$.
- (iv) $f : X \rightarrow X$ is said to be *p-continuous* if $\lim_{n \rightarrow \infty} p(x_n, x) = 0$ implies that $\lim_{n \rightarrow \infty} p(f(x_n), f(x)) = 0$.
- (v) $f : X \rightarrow X$ is $\tau(\Phi)$ -*continuous* if $\lim_{n \rightarrow \infty} x_n = x$ with respect to $\tau(\Phi)$ implies $\lim_{n \rightarrow \infty} f(x_n) = f(x)$ with respect to $\tau(\Phi)$.
- (vi) X is said to be *p-bounded* if $\delta_p = \sup\{p(x, y) | x, y \in X\} < \infty$.

Definition 6. Let (X, Φ) be a Hausdorff uniform space and p an *A-distance* on X . Two selfmappings f and g on X are said to be *p-compatible* if, for each sequence $\{x_n\}_{n=0}^\infty$ of X such that $\lim_{n \rightarrow \infty} p(f(x_n), u) = \lim_{n \rightarrow \infty} p(g(x_n), u) = 0$ for some $u \in X$, then we have $\lim_{n \rightarrow \infty} p(f(g(x_n)), g(f(x_n))) = 0$.

The following definition which is also required in the sequel to establish some common fixed point results is contained in Berinde [2], Rus [16] and Rus et al [17].

Definition 7. A function $\psi : \mathfrak{R}^+ \longrightarrow \mathfrak{R}^+$ is called a *comparison function* if

- (i) ψ is monotone increasing;
- (ii) $\lim_{n \rightarrow \infty} \psi^n(t) = 0, \forall t \geq 0$.

Remark 1. Every comparison function satisfies the condition $\psi(0) = 0$. Both conditions (i) and (ii) imply that $\psi(t) < t, \forall t > 0$. Our aim in this paper is to establish some common fixed point theorems by using the following contractive condition more general than (1), (2) and (3): Let $f, g : X \longrightarrow X$ be selfmappings of X . There exist $M \geq 0$ and comparison functions $\psi_1 : \mathfrak{R}^+ \longrightarrow \mathfrak{R}^+$ and $\psi_2 : \mathfrak{R}^+ \longrightarrow \mathfrak{R}^+$ with $\psi_1(0) = 0$ such that $\forall x, y \in X$, we have

$$p(f(x), f(y)) \leq \left(\psi_1(p(x, g(x))) + \psi_2(p(g(x), g(y))) \right) X \left(1 + Mp(x, g(x)) \right), \quad (4)$$

for all $x, y \in X$.

Remark 2. The contractive condition (4) is more general than (1), (2) and (3) in the sense that if $M = 0$ in (4), then we obtain

$$p(f(x), f(y)) \leq \psi_1(p(x, g(x))) + \psi_2(p(g(x), g(y))), \forall x, y \in X$$

which is the contractive condition employed by Bosede [6] in (3). Also, if $M = 0$ and $\psi_1(u) = Lu$ in (4), for $L \geq 0, u \in \mathfrak{R}^+$, then we obtain

$$p(f(x), f(y)) \leq Lp(x, g(x)) + \psi_2(p(g(x), g(y))), \forall x, y \in X$$

which is the contractive condition employed by Olatinwo [13] in (2).

Moreover, if $L = 0$ in the above inequality, then we obtain (1), which was employed by Aamri and El Moutawakil [1].

Thus, our contractive condition (4) is a generalization of the contractive definitions (1), (2) and (3) of Aamri and El Moutawakil [1], Olatinwo [13] and Bosede [6] respectively.

In the sequel, we shall require the following Lemma which is contained in Kang [12], Rodríguez-Montes and Charris [15] and Aamri and El Moutawakil [1].

Lemma 1. Let (X, Φ) be a Hausdorff uniform space and p an A -distance on X . Let $\{x_n\}_{n=0}^\infty, \{y_n\}_{n=0}^\infty$ be arbitrary sequences in X

and $\{\alpha_n\}_{n=0}^\infty, \{\beta_n\}_{n=0}^\infty$ be sequences in \mathfrak{R}^+ converging to 0. Then, for $x, y, z \in X$, the following hold:

- (a) If $p(x_n, y) \leq \alpha_n$ and $p(x_n, z) \leq \beta_n, \forall n \in N$, then $y = z$. In particular, if $p(x, y) = 0$ and $p(x, z) = 0$, then $y = z$.
- (b) If $p(x_n, y_n) \leq \alpha_n$ and $p(x_n, z) \leq \beta_n, \forall n \in N$, then $\{y_n\}_{n=0}^\infty$ converges to z .
- (c) If $p(x_n, x_m) \leq \alpha_n, \forall m > n$, then $\{x_n\}_{n=0}^\infty$ is a Cauchy sequence in (X, Φ) .

Remark 3. A sequence in X is p -Cauchy if it satisfies the usual metric property. [For Example, See Aamri and El Moutawakil [1]].

3. THE MAIN RESULTS

The following is the existence result for the common fixed point of f and g :

Theorem 1. Let (X, Φ) be a Hausdorff uniform space and p an A -distance on X such that X is p -bounded and S -complete. For arbitrary $x_0 \in X$, define a sequence $\{x_n\}_{n=0}^\infty$ iteratively by $x_n = f(x_{n-1}), n = 1, 2, \dots$

Suppose that f and g are commuting p -continuous or $\tau(\Phi)$ -continuous selfmappings of X such that

- (i) $f(X) \subseteq g(X)$,
- (ii) $p(f(x_i), f(x_i)) = 0, \forall x_i \in X, i = 0, 1, 2, \dots$,
- (iii) $f, g : X \rightarrow X$ satisfy the contractive condition (4) with $M \geq 0$.

Suppose also that $\psi_1 : \mathfrak{R}^+ \rightarrow \mathfrak{R}^+$ and $\psi_2 : \mathfrak{R}^+ \rightarrow \mathfrak{R}^+$ are comparison functions with $\psi_1(0) = 0$.

Then, f and g have a common fixed point.

Proof. For arbitrary $x_0 \in X$, select $x_1 \in X$ such that $f(x_0) = g(x_1)$. Similarly, for $x_1 \in X$, select $x_2 \in X$ such that $f(x_1) = g(x_2)$. Continuing this process, we select $x_n \in X$ such that $f(x_{n-1}) = g(x_n)$.

We shall show that the sequence $\{f(x_n)\}_{n=0}^\infty$ so generated is a p -Cauchy sequence.

Indeed, since $x_n = f(x_{n-1}), n = 1, 2, \dots$, then by using conditions (ii) and (iii) of the Theorem, we get

$$p(f(x_n), f(x_{n+m})) \leq \left(\psi_1(p(x_n, g(x_n))) + \psi_2(p(g(x_n), g(x_{n+m}))) \right) \left(1 + Mp(x_n, g(x_n)) \right)$$

$$\begin{aligned}
&= \left(\psi_1(p(f(x_{n-1}), f(x_{n-1}))) + \psi_2(p(f(x_{n-1}), f(x_{n+m-1}))) \right) \left(1 + \right. \\
&\quad \left. Mp(f(x_{n-1}), f(x_{n-1})) \right) \\
&= \left(\psi_1(0) + \psi_2(p(f(x_{n-1}), f(x_{n+m-1}))) \right) \left(1 + M(0) \right) \\
&= \left(0 + \psi_2(p(f(x_{n-1}), f(x_{n+m-1}))) \right) \left(1 + 0 \right) \\
&= \psi_2 \left(p(f(x_{n-1}), f(x_{n+m-1})) \right) \\
&\leq \psi_2 \left(\psi_1(p(x_{n-1}, g(x_{n-1}))) + \psi_2(p(g(x_{n-1}), g(x_{n+m-1}))) \right) \left(1 + \right. \\
&\quad \left. Mp(x_{n-1}, g(x_{n-1})) \right) \\
&= \psi_2 \left(\psi_1(p(f(x_{n-2}), f(x_{n-2}))) + \psi_2(p(f(x_{n-2}), f(x_{n+m-2}))) \right) \left(1 + \right. \\
&\quad \left. Mp(f(x_{n-2}), f(x_{n-2})) \right) \\
&= \psi_2 \left(\psi_1(0) + \psi_2(p(f(x_{n-2}), f(x_{n+m-2}))) \right) \left(1 + M(0) \right) \\
&= \psi_2 \left(0 + \psi_2(p(f(x_{n-2}), f(x_{n+m-2}))) \right) \left(1 + 0 \right) \\
&= \psi_2^2 \left(p(f(x_{n-2}), f(x_{n+m-2})) \right) \\
&\leq \dots \leq \psi_2^n(p(f(x_0), f(x_m))) \leq \psi_2^n(\delta_p(X)),
\end{aligned}$$

which implies that

$$p(f(x_n), f(x_{n+m})) \leq \psi_2^n(\delta_p(X)), \quad (5)$$

where $p(f(x_0), f(x_m)) \leq \delta_p(X)$ and

$\delta_p(X) = \sup\{p(x, y) | x, y \in X\} < \infty$.

Using the definition of comparison function in (5) gives

$$\lim_{n \rightarrow \infty} \psi_2^n(\delta_p(X)) = 0$$

and hence,

$p(f(x_n), f(x_{n+m})) \rightarrow 0$ as $n \rightarrow \infty$.

Therefore, by using Lemma 1(c), we have that $\{f(x_n)\}_{n=0}^\infty$ is a p -Cauchy sequence.

But X is S -complete. Hence, $\lim_{n \rightarrow \infty} p(f(x_n), u) = 0$, for some $u \in X$.

Since $x_n \in X$ implies that $f(x_{n-1}) = g(x_n)$, therefore, we have $\lim_{n \rightarrow \infty} p(g(x_n), u) = 0$.

Also, since f and g are p -continuous, then

$$\lim_{n \rightarrow \infty} p(f(g(x_n)), f(u)) = \lim_{n \rightarrow \infty} p(g(f(x_n)), g(u)) = 0.$$

But f and g are commuting, therefore $fg = gf$. Hence,

$$\lim_{n \rightarrow \infty} p(f(g(x_n)), f(u)) = \lim_{n \rightarrow \infty} p(f(g(x_n)), g(u)) = 0.$$

By applying Lemma 1(a), we have that $f(u) = g(u)$.

Since $f(u) = g(u)$ and $fg = gf$, then we have $f(f(u)) = f(g(u)) = g(f(u)) = g(g(u))$.

We need to show that $p(f(u), f(f(u))) = 0$. Suppose on the contrary that $p(f(u), f(f(u))) \neq 0$. By using the contractive definition (4) and the condition that $\psi(t) < t, \forall t > 0$ in the Remark 1, we obtain

$$\begin{aligned} p(f(u), f(f(u))) &\leq \left(\psi_1(p(u, g(u))) + \psi_2(p(g(u), g(f(u)))) \right) \left(1 \right. \\ &\quad \left. + Mp(u, g(u)) \right) \\ &= \left(\psi_1(p(f(u), f(u))) + \psi_2(p(f(u), f(f(u)))) \right) \left(1 + Mp(f(u), f(u)) \right) \\ &= \left(\psi_1(0) + \psi_2(p(f(u), f(f(u)))) \right) \left(1 + M(0) \right) \\ &= \left(0 + \psi_2(p(f(u), f(f(u)))) \right) \left(1 + 0 \right) \\ &= \psi_2(p(f(u), f(f(u)))) \\ &< p(f(u), f(f(u))), \end{aligned}$$

which is a contradiction. Hence, $p(f(u), f(f(u))) = 0$.

By using condition (ii) of the Theorem, we have $p(f(u), f(u)) = 0$. Therefore, since $p(f(u), f(f(u))) = 0$ and $p(f(u), f(u)) = 0$, by using Lemma 1(a), we get $f(f(u)) = f(u)$, which implies that $f(u)$ is a fixed point of f .

But, $f(u) = f(f(u)) = f(g(u)) = g(f(u))$, which shows that $f(u)$ is also a fixed point of g . Thus, $f(u)$ is a common fixed point of f and g .

The proof of when f and g are $\tau(\Phi)$ -continuous is similar since S -completeness implies p -Cauchy completeness.

This completes the proof.

Remark 4. The existence result in Theorem 1 is a generalization of Theorem 3.1 of Aamri and El Moutawakil [1], Theorem 3.1 of Olatinwo [13] as well as Theorem 3.1 of Bosede [6].

The next two Theorems establish the uniqueness of the common fixed point of f and g .

Theorem 2. Let $(X, \Phi), f, g, \psi_1, \psi_2, \{x_n\}_{n=0}^\infty$ be as defined in Theorem 1 above and p an E -distance on X . Then, f and g have a unique common fixed point.

Proof. Since an E -distance function p is also an A -distance, then by Theorem 1 above, we know that f and g have a common fixed point. Suppose that there exist $u, v \in X$ such that $f(u) = g(u) = u$ and $f(v) = g(v) = v$.

We need to show that $u = v$. Suppose on the contrary that $u \neq v$, i.e. let $p(u, v) \neq 0$.

Then, by using the contractive definition (4) and the condition that $\psi(t) < t$, $\forall t > 0$ in the Remark 1, we obtain

$$\begin{aligned} p(u, v) &= p(f(u), f(v)) \\ &\leq \left(\psi_1(p(u, g(u))) + \psi_2(p(g(u), g(v))) \right) (1 + Mp(u, g(u))) \\ &= \left(\psi_1(p(u, u)) + \psi_2(p(u, v)) \right) (1 + Mp(u, u)) \\ &= \left(\psi_1(0) + \psi_2(p(u, v)) \right) (1 + M(0)) \\ &= \left(0 + \psi_2(p(u, v)) \right) (1 + 0) \\ &= \psi_2(p(u, v)) \\ &< p(u, v), \end{aligned}$$

which is a contradiction. Hence, we have $p(u, v) = 0$.

Similarly, we have $p(v, u) = 0$. By applying condition (p_2) of Definition 3, we obtain $p(u, u) \leq p(u, v) + p(v, u)$, and hence $p(u, u) = 0$. Since $p(u, u) = 0$ and $p(u, v) = 0$, then by using Lemma 1(a), we get $u = v$.

This completes the proof.

Remark 5. The uniqueness result in Theorem 2 is a generalization of Theorem 3.2 as well as Corollaries 3.1 and 3.2 of Aamri and El Moutawakil [1].

Also, the uniqueness result in Theorem 2 is a generalization of Theorem 3.3 of Olatinwo [13] as well as Theorem 3.3 of Bosede [6].

Theorem 3. Let (X, Φ) , p , ψ_1 , ψ_2 and $\{x_n\}_{n=0}^\infty$ be as defined in Theorem 1 above. Suppose that f and g are p -compatible, p -continuous or $\tau(\Phi)$ -continuous selfmappings of X satisfying conditions (i), (ii) and (iii) of Theorem 1 above. Then, f and g have a unique common fixed point.

Proof. By Theorem 1 above, we know that f and g have a common fixed point. Hence, for some $u \in X$, we have $\lim_{n \rightarrow \infty} p(f(x_n), u) = \lim_{n \rightarrow \infty} p(g(x_n), u) = 0$.

Since f and g are p -continuous, then

$$\lim_{n \rightarrow \infty} p(f(g(x_n)), f(u)) = \lim_{n \rightarrow \infty} p(g(f(x_n)), g(u)) = 0.$$

Also, since f and g are p -compatible, then

$$\lim_{n \rightarrow \infty} p(f(g(x_n)), g(f(x_n))) = 0.$$

By applying condition (p_2) of Definition 3, we obtain

$$p(f(g(x_n)), g(u)) \leq p(f(g(x_n)), g(f(x_n))) + p(g(f(x_n)), g(u)).$$

Letting $n \rightarrow \infty$ and using Lemma 1(a) yields

$$\lim_{n \rightarrow \infty} p(f(g(x_n)), g(u)) = 0.$$

Since $\lim_{n \rightarrow \infty} p(f(g(x_n)), f(u)) = 0$ and $\lim_{n \rightarrow \infty} p(f(g(x_n)), g(u)) = 0$, then by Lemma 1(a), we obtain $f(u) = g(u)$.

The rest of the proof follows the same standard argument as in Theorem 1 and therefore it is omitted.

This completes the proof.

Remark 6. The uniqueness result in Theorem 3 is a generalization of Theorem 3.3 of Aamri and El Moutawakil [1]. Also, the uniqueness result in Theorem 3 is a generalization of Theorem 3.5 of Olatinwo [13] as well as Theorem 3.5 of Bosede [6].

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