

**STRONG CONVERGENCE OF A MODIFIED PICARD
PROCESS TO A COMMON FIXED POINT OF
A FINITE FAMILY OF LIPSCHITZIAN
HEMICONTRACTIVE MAPS**

Chika MOORE AND A. C. NNUBIA¹

ABSTRACT. Let K be a closed convex nonempty subset of a Hilbert space H and let the set of the common fixed points of a finite family of Lipschitzian hemicontractive maps from K into itself be non empty. Sufficient conditions for the strong convergence of the sequence of successive approximations generated by a Picard-like process to a common fixed point of the family are proved.

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1. INTRODUCTION

Let H be a Hilbert space and let K be a nonempty subset of H . K is said to be (sequentially) compact if every closed bounded sequence in K has a subsequence that converges in K . K is said to be boundedly compact if every bounded subset of K is compact. In finite dimensional spaces, closed subsets are boundedly compact. Given a subset S of K , we shall denote by $co(S)$ and $cl(S)$ the convex hull and the closed convex hull of S respectively. If K is boundedly compact convex and S is bounded, then $co(S)$ and hence $cl(S)$ are compact convex subsets of K .

A map $T : K \rightarrow E$ is said to be semi-compact if for any bounded sequence $\{x_n\} \subset K$ such that $\|x_n - Tx_n\| \rightarrow 0$ as $n \rightarrow \infty$ there exists a subsequence $\{x_{n_j}\} \subset \{x_n\}$ such that x_{n_j} converges strongly to some $x^* \in K$ as $j \rightarrow \infty$. The map T is said to be demi-compact at $z \in E$ if for any bounded sequence $\{x_n\} \subset K$ such that $\|x_n - Tx_n\| \rightarrow z$ as $n \rightarrow \infty$ there exist a subsequence $\{x_{n_j}\} \subset \{x_n\}$ and a point $p \in K$ such that x_{n_j} converges strongly to p as $j \rightarrow \infty$. (Observe that if T is additionally continuous, then $p - Tp = z$).

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¹Corresponding author

A nonlinear map $T : K \rightarrow E$ is said to be completely continuous if it maps bounded sets into relatively compact sets. Let T be a self-mapping on K . T is said to be Lipschitzian if $\exists L \geq 0$ such that

$$\|Tx - Ty\| \leq L\|x - y\|, \quad \forall x, y \in K. \quad (1)$$

If $L = 1$ then T is called *nonexpansive* and if $L < 1$ then the mapping T is called a contraction. The Mapping T with domain $D(T)$ and the range $R(T)$ in H is called pseudocontractive if $\forall x, y \in D(T)$,

$$\|Tx - Ty\|^2 \leq \|x - y\|^2 + \|(I - T)x - (I - T)y\|^2. \quad (2)$$

If (2) holds for all $x \in D(T)$ and $y \in F(T)$ (fixed point set of T), then T is said to be hemiccontractive.

The class of pseudocontractive maps has been extensively studied (see e.g [1]-[6] and the references therein). It is clear that the important class of nonexpansive mappings is a subclass of the class of pseudocontractive maps.

In [4], Ishikawa introduced a new iteration method and proved that it converges strongly to a fixed point of a Lipschitz pseudocontractive map defined on a compact convex subset of a Hilbert space. In fact, he proved the following result.

Theorem 1 (Ishikawa [4])

Let K be a compact convex nonempty subset of a Hilbert space and let $T : K \rightarrow K$ be a Lipschitz Pseudocontractive map. Let $\{\alpha_n\}, \{\beta_n\}$ be real sequences satisfying the following conditions:

- (1) $0 < \alpha_n \leq \beta_n < 1$.
- (2) $\lim_{n \rightarrow \infty} \beta_n = 0$.
- (3) $\sum \alpha_n \beta_n = \infty$.

Then starting with an arbitrary $x_0 \in K$ the sequence $\{x_n\}$ of successive approximations defined by

$$x_{n+1} = \alpha_n T[\beta_n T x_n + (1 - \beta_n)x_n] + (1 - \alpha_n)x_n; \quad n \geq 0, \quad (3)$$

converges strongly to a fixed point of T .

This result has been generalised in several ways by many authors see e.g. Li Qihou [5] who proved Theorem 1 in the case where T is a Lipschitz hemiccontraction. Chidume and Moore [1] who proved Theorem 1 in the case where T is a continuous hemiccontraction and for iteration process with errors, Ghosh and Debnath[3] who proved the convergence of a Picard-like process to a fixed point of a quasi-nonexpansive map.

Our purpose in this paper is to construct a Picard-like iteration process which converges strongly to a common fixed point of a finite family of Lipschitz hemicontractive self maps of a closed convex nonempty subset of a Hilbert space.

2. MAIN RESULT

We need the following lemma in this work.

Lemma 1: For any x, y, z in a Hilbert space H and a real number $\lambda \in [0, 1]$,

$$\begin{aligned} \|\lambda x + (1 - \lambda)y - z\|^2 &= \lambda\|x - z\|^2 + (1 - \lambda)\|y - z\|^2 \\ &\quad - \lambda(1 - \lambda)\|x - y\|^2. \end{aligned} \quad (4)$$

We define the following auxilliary maps: $\alpha, \beta \in (0, 1)$ constants;

$$S_{i\beta} = (1 - \beta)I + \beta T_i; \quad i \in \{1, 2, \dots, N\}. \quad (5)$$

$$T_{i\alpha\beta} = (1 - \alpha)I + \alpha T_i S_{i\beta}. \quad (6)$$

Theorem 1: Let H be a real Hilbert space and K a nonempty closed convex subset of H and let $\{T_i\}_{i=1}^N$ be a finite family of Lipschitzian (with constant $L_i > 0$) hemicontractive maps from K into itself such that $F = \bigcap_{i=1}^N F(T_i)$ is not empty. Let $L := \max_{1 \leq i \leq N} \{L_i\}$, and choose $\alpha, \beta \in (0, 1)$ such that $0 < \alpha < \beta < \frac{1}{1 + \sqrt{1 + L^2}}$. Starting with an arbitrary $x_0 \in K$, define the iterative sequence $\{x_n\}$ by

$$x_{n+1} = T_{i\alpha\beta} x_n; \quad n \geq 0 \quad n + 1 \equiv i \pmod{N}, \quad (7)$$

then

- (1) $\{x_n\}$ is bounded.
- (2) $\lim_{n \rightarrow \infty} \|x_n - x^*\|$ exists for $x^* \in F$.
- (3) $\forall i \in \{1, 2, \dots, N\}. \lim_{n \rightarrow \infty} \|x_n - T_i x_n\| = 0$.

Proof:

Let $x^* \in \bigcap_{i=1}^N F(T_i)$.

Now,

$$\begin{aligned}
 \|x_{n+1} - x^*\|^2 &= \|T_{i\alpha\beta}x_n - x^*\|^2 \\
 &= \|(1 - \alpha)x_n + \alpha T_i S_{i\beta}x_n - x^*\|^2 \\
 &= (1 - \alpha)\|x_n - x^*\|^2 + \alpha\|T_i S_{i\beta}x_n - x^*\|^2 \\
 &\quad - \alpha(1 - \alpha)\|T_i S_{i\beta}x_n - x_n\|^2 \\
 &\leq (1 - \alpha)\|x_n - x^*\|^2 + \alpha[\|S_{i\beta}x_n - x^*\|^2 \\
 &\quad + \|S_{i\beta}x_n - T_i S_{i\beta}x_n\|^2] \\
 &\quad - \alpha(1 - \alpha)\|T_i S_{i\beta}x_n - x_n\|^2.
 \end{aligned}$$

$$\begin{aligned}
 \|S_{i\beta}x_n - x^*\|^2 &= \|(1 - \beta)x_n + \beta T_i x_n - x^*\|^2 \\
 &= (1 - \beta)\|x_n - x^*\|^2 + \beta\|T_i x_n - x^*\|^2 \\
 &\quad - \beta(1 - \beta)\|T_i x_n - x_n\|^2 \\
 &\leq (1 - \beta)\|x_n - x^*\|^2 + \beta(\|x_n - x^*\|^2 \\
 &\quad + \|x_n - T_i x_n\|^2) - \beta(1 - \beta)\|T_i x_n - x_n\|^2 \\
 &= \|x_n - x^*\|^2 + \beta^2\|x_n - T_i x_n\|^2.
 \end{aligned}$$

Also,

$$\begin{aligned}
 \|S_{i\beta}x_n - T_i S_{i\beta}x_n\|^2 &= \|(1 - \beta)x_n + \beta T_i x_n - T_i S_{i\beta}x_n\|^2 \\
 &= (1 - \beta)\|x_n - T_i S_{i\beta}x_n\|^2 \\
 &\quad + \beta\|T_i x_n - T_i S_{i\beta}x_n\|^2 \\
 &\quad - \beta(1 - \beta)\|T_i x_n - x_n\|^2.
 \end{aligned}$$

But

$$\begin{aligned}
 \|T_i x_n - T_i S_{i\beta}x_n\|^2 &\leq L_i^2 \|x_n - S_{i\beta}x_n\|^2 \\
 &= L_i^2 \|x_n - (1 - \beta)x_n - \beta T_i x_n\|^2 \\
 &= \beta^2 L_i^2 \|x_n - T_i x_n\|^2 \\
 &\leq \beta^2 L^2 \|x_n - T_i x_n\|^2
 \end{aligned}$$

So that

$$\begin{aligned}
 \|S_{i\beta}x_n - T_i S_{i\beta}x_n\|^2 &\leq (1 - \beta)\|x_n - T_i S_{i\beta}x_n\|^2 \\
 &\quad + \beta^3 L^2 \|x_n - T_i x_n\|^2 \\
 &\quad - \beta(1 - \beta)\|T_i x_n - x_n\|^2 \\
 &= (\beta^3 L^2 + \beta^2 - \beta)\|x_n - T_i x_n\|^2 \\
 &\quad + (1 - \beta)\|x_n - T_i S_{i\beta}x_n\|^2.
 \end{aligned}$$

Hence

$$\begin{aligned}
\|x_{n+1} - x^*\|^2 &\leq (1 - \alpha)\|x_n - x^*\|^2 + \alpha[\|x_n - x^*\|^2 \\
&\quad + \beta^2\|x_n - T_i x_n\|^2 \\
&\quad + (\beta^3 L^2 + \beta^2 - \beta)\|x_n - T_i x_n\|^2 \\
&\quad + (1 - \beta)\|x_n - T_i S_{i\beta} x_n\|^2] \\
&\quad - \alpha(1 - \alpha)\|x_n - T_i S_{i\beta} x_n\|^2. \\
&= \|x_n - x^*\|^2 - \alpha\beta(1 - 2\beta - \beta^2 L^2)\|x_n - T_i x_n\|^2 \\
&\quad - \alpha(\beta - \alpha)\|x_n - T_i S_{i\beta} x_n\|^2 \\
&\leq \|x_n - x^*\|^2 - \alpha\beta(1 - 2\beta - \beta^2 L^2)\|x_n - T_i x_n\|^2.
\end{aligned}$$

Thus,

$$\begin{aligned}
\|x_{n+1} - x^*\|^2 &\leq \|x_n - x^*\|^2 - c\alpha\beta\|x_n - T_i x_n\|^2 \\
&\leq \|x_n - x^*\|^2,
\end{aligned}$$

where $c := 1 - 2\beta - \beta^2 L^2 > 0$. Thus, conditions (1) and (2) above hold.

Now $\forall i \in \{1, 2, \dots, N\}$,

$$c\alpha\beta\|x_n - T_i x_n\|^2 \leq \|x_n - x^*\|^2 - \|x_{n+1} - x^*\|^2. \quad (8)$$

Hence, summing above equation from $n = 0$ and observing that the right hand side telescopes, we have

$$c\alpha\beta \sum_{n \geq 0} \|x_n - T_i x_n\|^2 \leq \|x_0 - x^*\|^2 < \infty; \forall i \in \{1, \dots, N\}.$$

Thus,

$$\sum_{n \geq 0} \|x_n - T_i x_n\|^2 < \infty; \forall i \in \{1, \dots, N\}.$$

Which implies that

$$\lim_{n \rightarrow \infty} \|x_n - T_i x_n\| = 0; \forall i \in \{1, \dots, N\}. \quad (9)$$

This completes the proof.

Remark 1: Suppose that $\{x_n\}$ has a convergent subsequence $\{x_{n_j}\}$. Let $x_{n_j} \rightarrow p$ as $j \rightarrow \infty$. Since $x_n - T_i x_n \rightarrow 0$ as $n \rightarrow \infty \forall i \in \{1, 2, \dots, N\}$. it implies that $x_{n_j} - T_i x_{n_j} \rightarrow 0$ as $j \rightarrow \infty \forall i \in I$ and that $T_i x_{n_j} \rightarrow T_i p$ as $j \rightarrow \infty \forall i$ by continuity of T_i . So, $\|p - T_i p\| = \lim_{n \rightarrow \infty} \|x_{n_j} - T_i x_{n_j}\| = 0, \forall i$ implying that $p \in F$. Thus, $\|x_{n+1} - p\| \leq \|x_n - p\|$ and $\lim_{n \rightarrow \infty} \|x_n - p\|$ exists but $\lim_{n \rightarrow \infty} \|x_{n_j} - p\| = 0$, so $\lim_{n \rightarrow \infty} \|x_n - p\| = 0$. Hence $x_n \rightarrow x^*(=p)$ as $n \rightarrow \infty$.

Conditions under which $\{x_n\}$ has a convergent subsequence include

- (1) T_i is completely continuous $\forall i \in \{1, \dots, N\}$.
- (2) T_i is demicompact $\forall i \in \{1, \dots, N\}$.
- (3) T_i is semicompact for some $i \in \{1, \dots, N\}$.
- (4) K is compact.
- (5) K is boundedly compact.

A map $A : H \rightarrow H$ is said to be accretive or monotone if $\forall x, y \in H$ and $\forall \alpha > 0$

$$\|x - y + \alpha(Ax - Ay)\| \geq \|x - y\|. \quad (10)$$

If the above holds $\forall x \in H$ and $\forall y \in Z(A) := \{w \in H | Aw = 0\}$ (the zero set of A), then A is said to be quasi-accretive. It is easy to see that T is hemiccontractive if and only if $A = I - T$ is quasi-accretive. Now, let

$$G_{i\beta} = I - \beta A_i; \quad i \in \{1, \dots, N\}. \quad (11)$$

$$A_{i\alpha\beta} = I - \alpha\beta A_i - \alpha A_i G_{i\beta}. \quad (12)$$

We have the following theorem as an easy corollary to Theorem 2.1.

Theorem 2: Let H be a real Hilbert space and let $A_i : H \rightarrow H; i \in \{1, 2, \dots, N\}$ be a finite family of L_i -Lipschitzian quasi-accretive maps such that the simultaneous nonlinear equations $A_i x = 0; i \in \{1, 2, \dots, N\}$ have a solution $x^* \in H$. Let $L := \max_{1 \leq i \leq N} \{L_i\}$, and choose $\alpha, \beta \in (0, 1)$ such that $0 < \alpha < \beta < \frac{1}{1 + \sqrt{1 + L^2}}$. Starting with an arbitrary $x_0 \in H$ define the iterative sequence $\{x_n\}$ by

$$x_{n+1} = A_{i\alpha\beta} x_n; \quad n \geq 0; \quad n + 1 \equiv i \pmod{N}. \quad (13)$$

then

- (1) $\{x_n\}$ is bounded.

$$\text{item } \lim_{n \rightarrow \infty} \|x_n - x^*\| \text{ exists } \forall x^* \in \bigcap_{i=1}^N Z(A_i).$$

- (2) $\lim_{n \rightarrow \infty} \|A_i x_n\| = 0; \quad \forall i \in \{1, 2, \dots, N\}$.

Proof:

Let $T_i = I - A_i$. Then T_i is a Lipschitzian hemiccontraction. Further,

$$\begin{aligned} S_{i\beta} &= (1 - \beta)I + \beta T_i = I - \beta(I - T_i) = I - \beta A_i = G_{i\beta}. \\ T_{i\alpha\beta} &= (1 - \alpha)I + \alpha T_i S_{i\beta} = I - \alpha(I - G_{i\beta}) - \alpha A_i G_{i\beta} \\ &= I - \alpha\beta A_i - \alpha A_i G_{i\beta} = A_{i\alpha\beta}. \end{aligned}$$

Thus, Theorem 2.1 applies and we have the stated results.

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DEPARTMENT OF MATHEMATICS, NNAMDI AZIKWE UNIVERSITY, AWKA, NIGERIA

E-mail addresses: drchikamoore@yahoo.com, chikamoore@unizik.edu.ng

DEPARTMENT OF MATHEMATICS, NNAMDI AZIKWE UNIVERSITY, AWKA, NIGERIA

E-mail address: obijiakuagatha@ymail.com